

## TCP Connection Module

The TCP Connection Module adds an additional TCP interface to myP through which the robot can be controlled. myP runs a TCP server which is available for clients as soon as the robot is powered on. All commands that are usually issued by the browser (such as connecting, calibrating and starting applications) can be sent to the robot via the TCP interface. The interface can also be used to make the robot control the clients. Most customers use this module to control the robot from their own software.