

## Fingers

Each finger of P-Grip contains up to four proximity sensors that can be used to recognize and grip objects. The fingers are exchangeable and connected by only one screw each. Fitting size and length of a screw must be carefully chosen. The size and type of fingers can be chosen depending on your preferred shape and number of sensors and according to your application.

The shape of the fingers allows to grasp everything from small objects to objects as large as the opening angle of the gripper.

